

MILNICOX PICNLOX F4C PC



# ClearMotion





**Technical Deep Dive** 

### Video Demonstration: Super-Active Ride Control



# Constant Tradeoff: Ride vs. Handling



Two cars in one: Industry pursuit over 30 years, no solution yet.

### **Novel Approach:** Local electrohydraulics and controls



**Product Overview** 

### **Technical Deep Dive**



System Architecture Deconstruction of a bump Performance & Tuning Embedded Software Architecture

### **GenShock System Architecture**



GenShock Fundamentals

# **Hydraulic Principle**

#### Passive Quadrants (I and III)

- · Oil Flow through the valve in both directions
- · Volume of the piston rod is compensated by the gas accumulator
- Gas pressure supports rebound forces
- Hydraulic pump acts like a variable damping valve for oil flow in extension and compression



GenShock Fundamentals

# Hydraulic Principle (cont.)

#### Active Quadrants (II and IV)

- Activalve is able to supply oil volume independent of the stroke
- Thus, it can increase or decrease pressure acting on the piston



**Product Overview** 

**Technical Deep Dive** 

System Architecture



Deconstruction of a bump

Performance & Tuning

Embedded Software Architecture

## Full active control Speed bump example



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### GenShock vs. Passive Roll Rate: Offset Bumps



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### **Roll Curve Tunability & Power Tradeoffs**



# **Noise Cancellation Algorithms**



Rod acceleration is reduced dramatically at the 1<sup>st</sup> harmonic

Product Overview Technical Deep Dive System Architecture Deconstruction of a bump Control Loop Timing Performance & Tuning Embedded Software Architecture



# **GenShock Corner Application Software Architecture**

- Bare metal application for increased performance
- Model based design with Matlab/Simulink enables accelerated development
- Control abstraction layers create robust, verifiable design
- Standards based protocol implementations for ease of integration with OEM's

# **GenShock Central Application Software Architecture**

- Coordinated control of vehicle dynamics (cornering, braking, accelerating, etc.)
- System state management (power on/off, fault management, etc.)
- Intelligent power control
- System software update

